

Designing the Lakeland Repeater (WR4 AWJ) Control and Identify Program

By Bill Hunsicker (K4DF/W5HKM)

An old college friend, George P. Burdell, dropped by to see me not too long ago. After trading a few amenities, we began discussing computer applications.

"Bill, I had an idea about using a microcomputer to run the Lakeland Amateur Radio Repeater."

"I knew it! OK, I can give you some of what you want, but just what are we setting out to accomplish? In other words, what are our goals? Here, let me show you what I mean." I then wrote 9 goals on the blackboard:

GOALS

1. Recognize input signals. (COR and others later on)
2. Control the repeater transmitter.
3. Keep accurate time. (transparent to current operations)

4. Perform ID on a time scheduled basis.
 5. Maintain and update internal timers.
 6. Provide windbag, tailgate and transmitter time-out control.
 7. Provide tone-modulated code. (also transparent)
 8. Provide a "Kerchunk" filter.
 9. Provide for future growth. (Phone-Patch, etc.)
- I said, "The next thing we should do is to define the steps that need to be accomplished."

George interrupted me. "Then we need to develop a flow chart, write the program, develop the hardware. . ." Our list grew to a total of eight items.

STEPS TO ACCOMPLISH

1. Develop list of goals.
2. Develop Flowchart.

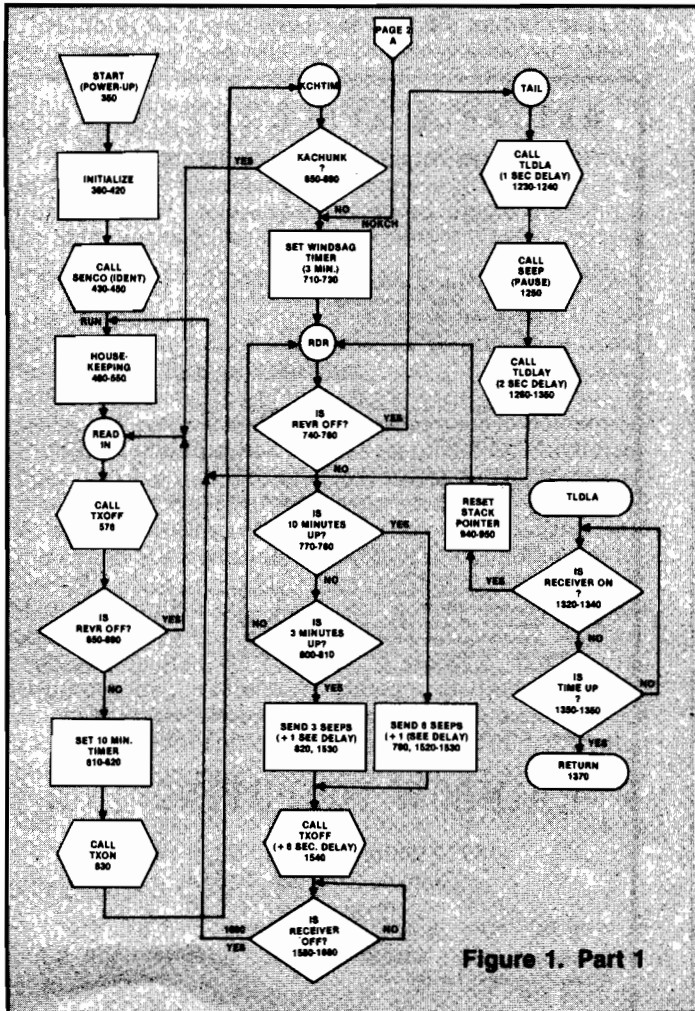


Figure 1. Part 1

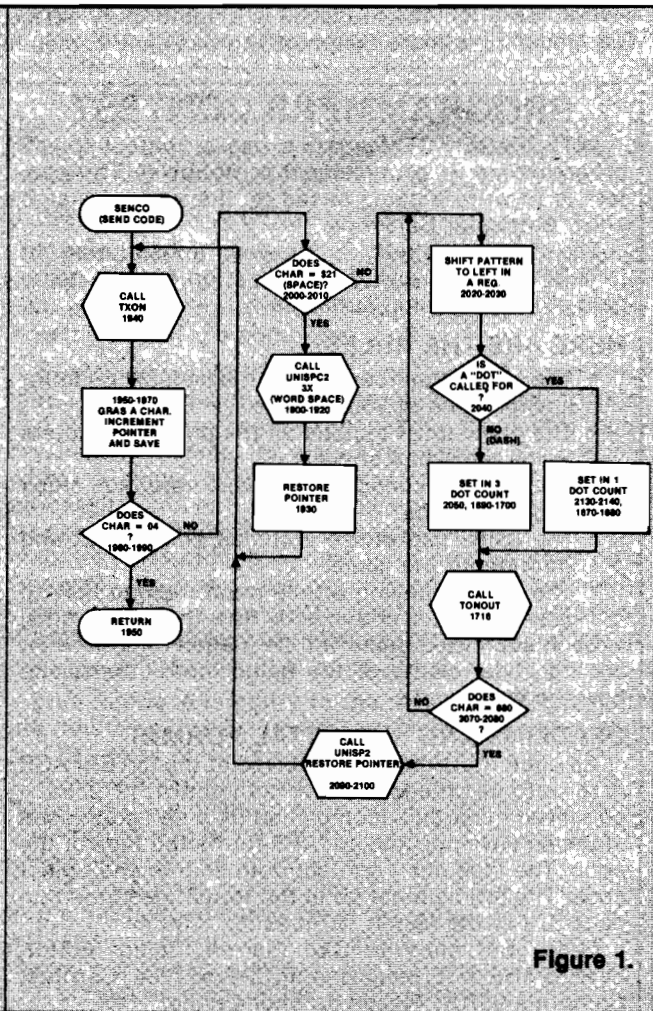


Figure 1.

3. Write the program and develop hardware circuit.
4. Simulate and debug the software and hardware.
5. Convert the software to firmware (EPROM).
6. Build hardware.
7. Connect to Repeater.
8. Plan enhancements.

"Now that we have come this far, George, we have reached a milestone. We have done the preliminary planning. I anticipated a request like yours; steps 1 through 5 of the 'steps to accomplish' have already been done!"

"Here is a copy of the assembled program listing (Program 1), and the schematic (Figure 1). Now then, if you will take the program to your friendly microcomputer store, have them program a 2708 EPROM for you and then build the circuit I gave you, you are almost home free."

"Hey, that's fantastic, Bill. It's more than I had even hoped for. But I'd like to know how this thing works. Suppose it sent the code too fast or too slow, or that the call letters have to be changed? What about..."

"Thought you'd never ask, George. The main program starts at the label START where system initialization is performed. Once the system has been initialized, the computer will fall into a loop at label READIN (lines 570-600) where the transmitter will be turned off. The system will then wait for an indication that the receiver has detected a carrier (HEX bit 01). After a carrier has been detected, the computer will proceed to set the ten minute timer (maximum transmitter on-time) and to turn

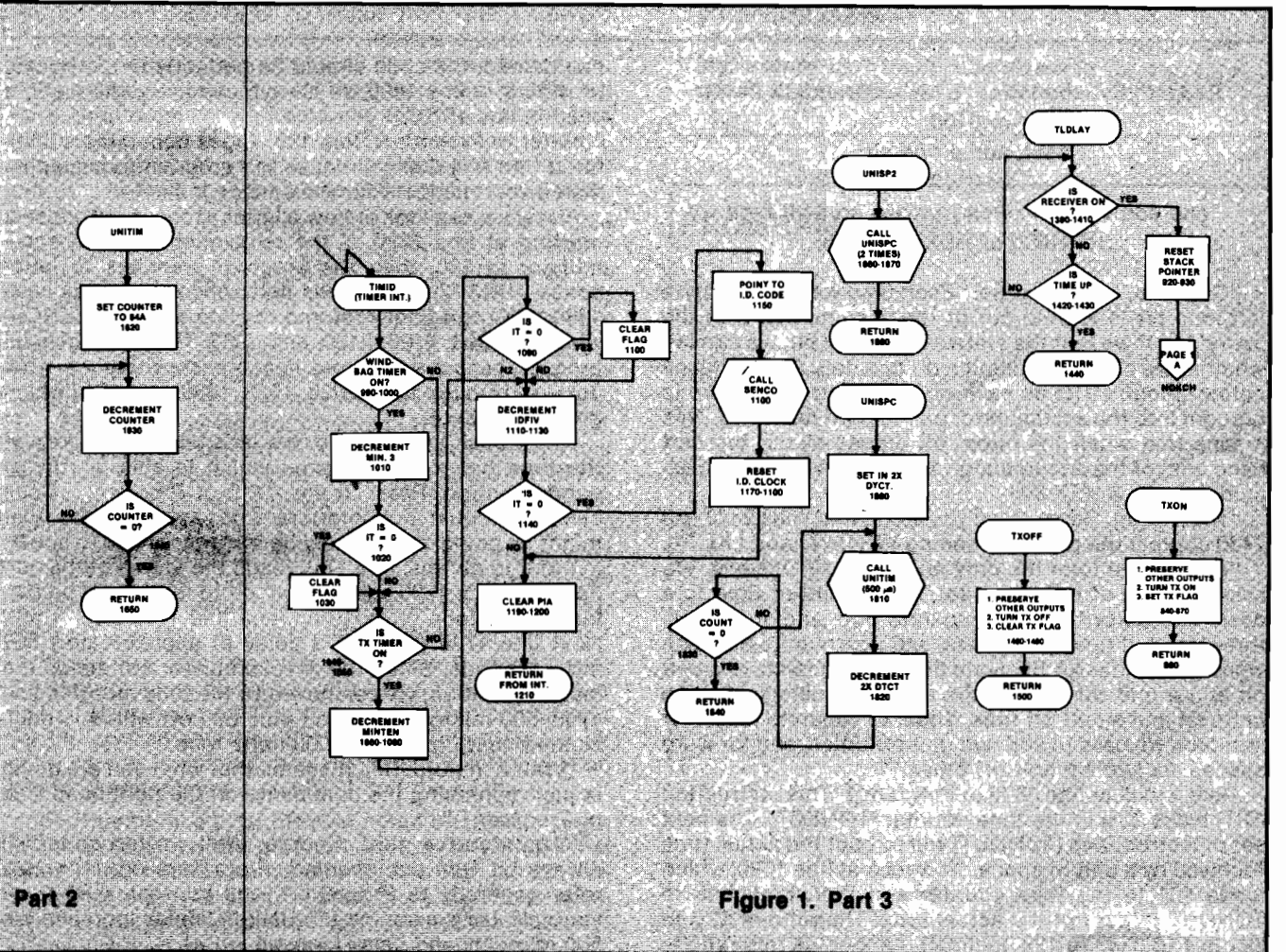
the transmitter on. While the transmitter is keyed, the operational loop at RDR (lines 740-810) is in control of the system.

"There are two main support routines in the program. One of the main subroutines is TIMID, which is the time keeping routine activated by the hardware clock ticks. The other subroutine is SENCO, the code sending routine.

"First off, let's see how the code is sent. Before SENCO is called, the index register (line 1150) is pointed at the code buffer IDENT. The transmitter is turned on at line 1960, the first byte is loaded into the A accumulator (line 1970), and then the index register is incremented by one and saved. Now we check to see if the A accumulator contains the terminator for sending code (end of transmission is a hexadecimal 04). If it does, we go back to the caller; else we check to see if it is a space between words (HEX 21).

"If it was a word space we do a WRDSPC; if not, we do an arithmetic shift left, push the A accumulator on the stack (to save it) and check to see if there is a carry. If there is a carry, we transmit DAH (dash); if not, we transmit a DIT (dot). Next we retrieve the value we saved in the stack and put it back into the A accumulator. If the character was a HEX 80, we transmit a letter space and re-enter the routine at SENCO. If the character retrieved was not a HEX 80, we do another arithmetic shift left (ASL), and so on.

"Let me show you how to construct a code message. You see, we let zeros be dits and the ones be dahs, all to be followed by a one."



Part 2

Figure 1. Part 3

"Line 1820 seems to infer that we need a space twice as long as a dit. Actually, a dit is turned on for 500 microseconds and then off for 500 more. Therefore, to equal the length of a dit, we must have two 500 microsecond delays for each dit count (DTCT). Thus, we use lines 1820 through 1860 to obtain a delay equal to a dit time.

"The 500 microsecond delay loop, on the other hand, is a little more sticky and is the basis of most of our delays. The crystal clock assumed is approximately 1.797 Mhz which makes each machine cycle approximately 1.113 microseconds long. If we trace the program from line 1620 through lines 1630, 1640, 1650 and back, we will have consumed 445 machine cycles. 445*1.11 microseconds per machine cycle is approximately 495 microseconds."

"Bill, if all the timing is developed by your 500 microsecond delay loop, why on the schematic (Figure 1) do you have a 4024 and 4020 identified as a ID TIMER? It seems to be attached to the 6800 NMI input. Isn't that being used as a 'timer' of sorts?"

"There are two general types of timing employed by the program. One we have just examined is related to the system master crystal controlled clock to generate the 500 microsecond delays. There is another form of timing that depends on a hardware clock. The reason is, if we tied the CPU up in being a software clock, it would be hard-pressed to do anything else. Note that the 500 microsecond delays are when it is doing a specific chore (sending code) and almost everything else stays in a 'status-quo' condition. Almost everything, that is. We do allow interrupts to occur from the hardware clock. My simulations using the hardware clock tied to the non-maskable interrupt (NMI) line showed the clock ticks to be unnoticeable. If they were noticeable, we have an alternative; we could use the interrupt request (IRQ) line which is maskable. The difference is negligible, and at worst we would only lose several seconds out of every five minutes while sending the ident code.

"If we want to use the hardware clock (4020 and 4024 dividers) for IRQ operation, it probably would be better to open a link (CB2 to GND) and configure the 6820 PIA for interrupts through the IRQB line. In this case, we must do a 'read' in the TIMID routine. See Figure 1. Line 2490 will have to be changed to a "FDB TIMID" instruction and line 2510 changed to "RMB 1". This now vectors us into the time clock routine via the interrupt on IRQB.

"With the hardware clock made of the 4024 and 4020, the closest to a 1 second time tick that could be obtained reasonably was .88 seconds. Thus lines 460, 610 and 710 contained calibrated numbers which provide the desired timings.

"Another approach would be to use presettable counters to give exactly one second or to use another 555 timer, free running, with an adjustment to put it exactly on one second pulses. (My simulation does this.)

"Since we are discussing different approaches, Motorola has just come out with a new CPU (which they call MPU). It is the 6802. It has the 6871A clock (except for the crystal) and the 6810 built in. This means a TV color crystal can probably be tied directly to two pins on the 6802 and eliminate the 6871 and the 6810.

"Furthermore, a 2704 EPROM could be used in place of the 2708 since the program uses only 427 decimal bytes. I do not recommend this, however, since this should only be the start of something big! Later additions to the program can do various neat things, occasionally calling on the already existing routines."

"How about phone patches, weather bulletins, off frequency reports, and so on?"

"Let me make an off-hand comment, George. This program has not been optimized, and there are places where the index register was used to permit 16 bit arithmetic to allow for the slower code speeds in case someone should want to lift the SENCO subroutine for some other code sending application. But for now, this is very convenient for us."□

ACKNOWLEDGEMENT

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ABOUT THE AUTHOR

Bill Hunsicker, K4DF/W5HKM, age 53, is a professional engineer #3544 Oklahoma. He received his amateur license at age 14, and graduated from Georgia Tech with BEE in 1951. He served in the Navy during World War II, has a private pilot's license, and a radio telephone license first class.

He took up personal computer programming a little over a year ago, and took a 3-day cram course from Motorola on the 6800. He has found that programming in software is just a step forward from what he had been doing in hardware decision making, except that trading hardware in for software opens a vast new field.

PROGRAM LISTING

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00150          * DTCT: $2B/20WPM, $3B/15WPM, $6B/10WPM
00160          OPT      0
00170          *
00180          4004    PIAD    FCU    $4004    OUTPUTS
00190          4025    FIAC    FCU    $4005
00200          4026    PIBD    FCU    $4006    INPUTS
00210          4027    PIBC    EQU    $4007
00220          002F    STK    EQU    $7F
00230          002F    DTCT    EQU    $2B    DIT COUNT
00240          *
00250    0000          ORG      53
00260    0000    0001    MINS    RMB    1
00270    0001    0002    MINTFN  RMB    2
00280    0003    0002    IDFIV   RMP    2
00290    0005    0002    XTEMP   RMP    2
00300    0007    0002    TCNFACT  RMB    2
00310    0009    0001    TXFLG   RMB    1
00320    000A    0001    WINFLG   RMB    1
00330          *
00340    8000          ORG      $8000
00350    8000    01          START  NCP
00360    8001    0F          SEI
00370    8002    CF    FF1F    LDX      #FF1F    SET INT MASK
00380    8005    FF    4024    STX      PIAD    IN A SIDE
00390    8008    CE    001F    LDX      $51F   ALL INPUTS
00400    800B    FF    4025    STX      PIBD    IN E SIDE
00410    800E    0E    007F    LDS      #STK   SET STACK
00420    8011    CE    8190    LDX      #IDENT  IDENTIFY
00430    8014    FD    8145    JSR      SENCO  IDENT CODE
00440    8017    CE    819F    LDX      #RFSET  CODE IDENT
00450    801A    FD    8145    JSR      SENCO  SEND CODE

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