Designing the Lakeland Repeater (WR4 AWJ) Control and Identify Program

By Bill Hunsicker (K4DF/W5HKM)

An old college friend, George P. Burdell, dropped by to see me not too long ago. After trading a few amenities, we began discussing computer applications.

"Bill, I had an idea about using a microcomputer to

run the Lakeland Amateur Radio Repeater.'

"I knew it! OK, I can give you some of what you want, but just what are we setting out to accomplish? In other words, what are our goals? Here, let me show you what I mean." I then wrote 9 goals on the blackboard:

GOALS

- Recognize input signals. (COR and others later on)
- 2. Control the repeater transmitter.
- 3. Keep accurate time. (transparent to current operations)

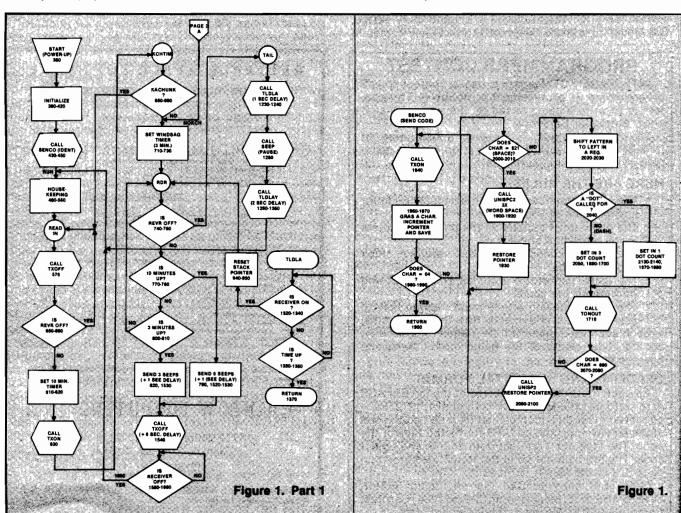
- Perform ID on a time scheduled basis.
- Maintain and update internal timers.
- 6. Provide windbag, tailgate and transmitter timeout control.
- 7. Provide tone-modulated code. (also transparent)
- 8. Provide a "Kerchunk" filter.
- 9. Provide for future growth. (Phone-Patch, etc.)

I said, "The next thing we should do is to define the steps that need to be accomplished."

George interrupted me. "Then we need to develop a flow chart, write the program, develop the hardware. . . Our list grew to a total of eight items.

STEPS TO ACCOMPLISH

- Develop list of goals.
- 2. Develop Flowchart.



- 3. Write the program and develop hardware circuit.
- 4. Simulate and debug the software and hardware.
- 5. Convert the software to firmware (EPROM).
- 6. Build hardware.
- 7. Connect to Repeater.
- 8. Plan enhancements.

"Now that we have come this far, George, we have reached a milestone. We have done the preliminary planning. I anticipated a request like yours; steps 1 through 5 of the 'steps to accomplish' have already been done!"

"Here is a copy of the assembled program listing (Program 1), and the schematic (Figure 1). Now then, if you will take the program to your friendly microcomputer store, have them program a 2708 EPROM for you and then build the circuit I gave you, you are almost home free."

"Hey, that's fantastic, Bill. It's more than I had even hoped for. But I'd like to know how this thing works. Suppose it sent the code too fast or too slow, or that the call letters have to be changed? What about. . ."

"Thought you'd never ask, George. The main program starts at the label START where system initialization is performed. Once the system has been initialized, the computer will fall into a loop at label READIN (lines 570-600) where the transmitter will be turned off. The system will then wait for an indication that the receiver has detected a carrier (HEX bit 01). After a carrier has been detected, the computer will proceed to set the ten minute timer (maximum transmitter on-time) and to turn

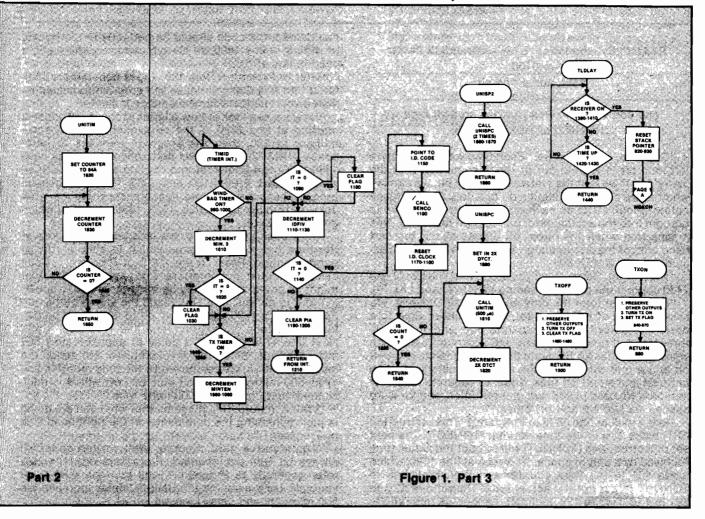
the transmitter on. While the transmitter is keyed, the operational loop at RDR (lines 740-810) is in control of the system.

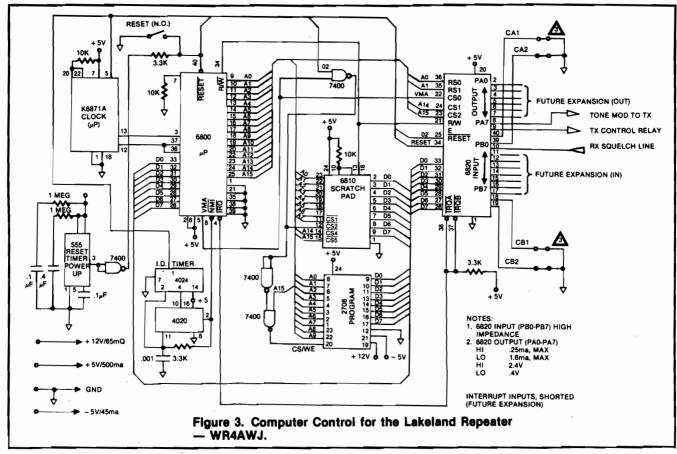
"There are two main support routines in the program. One of the main subroutines is TIMID, which is the time keeping routine activated by the hardware clock ticks. The other subroutine is SENCO, the code sending routine.

"First off, let's see how the code is sent. Before SENCO is called, the index register (line 1150) is pointed at the code buffer IDENT. The transmitter is turned on at line 1960, the first byte is loaded into the A accumulator (line 1970), and then the index register is incremented by one and saved. Now we check to see if the A accumulator contains the terminator for sending code (end of transmission is a hexadecimal 04). If it does, we go back to the caller; else we check to see if it is a space between words (HEX 21).

"If it was a word space we do a WRDSPC; if not, we do an arithmetic shift left, push the A accumulator on the stack (to save it) and check to see if there is a carry. If there is a carry, we transmit DAH (dash); if not, we transmit a DIT (dot). Next we retrieve the value we saved in the stack and put it back into the A accumulator. If the character was a HEX 80, we transmit a letter space and re-enter the routine at SENCO. If the character retrieved was not a HEX 80, we do another arithmetic shift left (ASL), and so on.

"Let me show you how to construct a code message. You see, we let zeros be dits and the ones be dahs, all to be followed by a one."





EXAMPLE: the letter "L" is a didahdidit (.—..) or 0100 next, add a one bit: or 01001

and add enough zeros to make an 8-bit byte: 01001000 or HEX 48 (\$48)

"Oh, I see," said George. "Each time we shift the byte left, one bit is shifted out of the accumulator into the 'carry' bit. If we test the state of the carry bit, we can tell whether we should transmit a dit or a dah. But the fascinating thing is that as each bit is shifted left, a zero is brought into the accumulator on the right hand end. This means that when the 'stop' bit arrives at the top (left hand end) of the accumulator, the actual value of the accumulator is a HEX 80."

"That's right, George, and you'll find that lines 2420 and 2430 contain the data for sending WR4AWJ and LKL FL.

"How do we form the dots and dashes? Observe. We assign a unit of time to a dot, three units of time to a dash, one unit of time to separate dots and/or dashes, three units of time characters, and seven units between words. Consider AA EE. Note that a dit consists of a unit on and a unit off time, while a dash consists of three units on and a unit off time. Thus, to separate letters or numbers we have to add two unit off times, and for word spaces we add six unit off times."

Take a look at line 1670 in Program 1. This instruction (DIT) loads \$2B in the tone counter (TONECT). The next set of instructions (TONOUT) will put out the actual tone followed by a unit of space. Now look at line 1690, which loads \$81 in the tone counter and then branches to TONOUT to put out the actual tone. The ratio of \$2B to \$81 is 1 to 3 (43 to 129 decimal). As long as this ratio is

maintained, the code should be perfectly proportioned, providing in line 1800 we always use twice the number used in line 1670.

Refer to Program 1, line 150. These constants substituted into line 230 will cause the program to assemble the correct numbers for the speeds indicated.

"Now we can look at how a letter space is introduced, starting at line 2090. If the remainder of the A accumulator is \$80, then the program branches to letter space (UNISP2) which calls unit space twice (see lines 1880-1890) and finally returns to code sending (SENCO) via lines 1900, 2120, 2130, and 1960. The same general process happens for word space except that we work our way through lines 2030, 1920, 1930, and 1940 which gives us 3*2=6.

"That wasn't so hard, so now let's take a close look at the tone generation scheme which is also worthy of some mention. Refer to line 1710 of Program 1. Code sending should not interfere with anything else that might be going on; it should be transparent, so to speak. In order to do this, line 1710 reads the status of the output lines, line 1720 adds an 'on' bit to the output bit pattern in the tone bit position, and line 1730 puts it out. Next line 1740 goes for a delay of approximately 500 microseconds. Since the A accumulator still holds the last information, we can now turn the tone bit off in line 1760. 500 microseconds on plus 500 off will be 1 millisecond, just right for a 1000 hertz tone."

"Wait a minute, Bill, it seems that what you are doing is just rephrasing the comments on the right hand side of Program 1."

"Again you're right, George. Well written code will always be well documented. From here on, let's only refer generally to Program 1, and you can read it for yourself. Let's examine the UNISPC delay loop and the 500 microsecond delay loop.

SOFTWARE APPLICATION

"Line 1820 seems to infer that we need a space twice as long as a dit. Actually, a dit is turned on for 500 microseconds and then off for 500 more. Therefore, to equal the length of a dit, we must have two 500 microsecond delays for each dit count (DTCT). Thus, we use lines 1820 through 1860 to obtain a delay equal to a dit time.

"The 500 microsecond delay loop, on the other hand, is a little more sticky and is the basis of most of our delays. The crystal clock assumed is approximately 1.797 Mhz which makes each machine cycle approximately 1.113 microseconds long. If we trace the program from line 1620 through lines 1630, 1640, 1650 and back, we will have consumed 445 machine cycles. 445*1.11 microseconds per machine cycle is approximately 495 microseconds."

"Bill, if all the timing is developed by your 500 microsecond delay loop, why on the schematic (Figure 1) do you have a 4024 and 4020 identified as a ID TIMER? It seems to be attached to the 6800 NMI input. Isn't that being used as a 'timer' of sorts?"

"There are two general types of timing employed by the program. One we have just examined is related to the system master crystal controlled clock to generate the 500 microsecond delays. There is another form of timing that depends on a hardware clock. The reason is, if we tied the CPU up in being a software clock, it would be hard-pressed to do anything else. Note that the 500 microsecond delays are when it is doing a specific chore (sending code) and almost everything else stays in a 'status-quo' condition. Almost everything, that is. We do allow interrupts to occur from the hardware clock. My simulations using the hardware clock tied to the non-maskable interrupt (NMI) line showed the clock ticks to be unnoticeable. If they were noticeable, we have an alternative; we could use the interrupt request (IRQ) line which is maskable. The difference is negligible, and at worst we would only lose several seconds out of every five minutes while sending the ident code.

"If we want to use the hardware clock (4020 and 4024 dividers) for IRQ operation, it probably would be better to open a link (CB2 to GND) and configure the 6820 PIA for interrupts through the IRQB line. In this case, we must do a 'read' in the TIMID routine. See Figure 1. Line 2490 will have to be changed to a "FDB TIMID" instruction and line 2510 changed to "RMB 1". This now vectors us into the time clock routine via the interrupt on IRQB.

"With the hardware clock made of the 4024 and 4020, the closest to a 1 second time tick that could be obtained reasonably was .88 seconds. Thus lines 460, 610 and 710 contained calibrated numbers which provide the desired timings.

"Another approach would be to use presettable counters to give exactly one second or to use another 555 timer, free running, with an adjustment to put it exactly on one second pulses. (My simulation does this.)

"Since we are discussing different approaches, Motorola has just come out with a new CPU (which they call MPU). It is the 6802. It has the 6871A clock (except for the crystal) and the 6810 built in. This means a TV color crystal can probably be tied directly to two pins on the 6802 and eliminate the 6871 and the 6810.

"Furthermore, a 2704 EPROM could be used in place of the 2708 since the program uses only 427 decimal bytes. I do not recommend this, however, since this should only be the start of something big! Later additions to the program can do various neat things, occasionally calling on the already existing routines."

"How about phone patches, weather bulletins, off frequency reports, and so on?"

"Let me make an off-hand comment, George. This program has not been optimized, and there are places where the index register was used to permit 16 bit arithmetic to allow for the slower code speeds in case someone should want to lift the SENCO subroutine for some other code sending application. But for now, this is very convenient for us."

ACKNOWLEDGEMENT

I would like to thank Brand-Rex, Teltronics Division for the use of their high speed printer which saved much time on this project.

ABOUT THE AUTHOR

Bill Hunsicker, K4DF/W5HKM, age 53, is a professional engineer #3544 Oklahoma. He received his amateur license at age 14, and graduated from Georgia Tech with BEE in 1951. He served in the Navy during World War II, has a private pilot's license, and a radio telephone license first class.

He took up personal computer programming a little over a year ago, and took a 3-day cram course from Motorola on the 6800. He has found that programming in software is just a step forward from what he had been doing in hardware decision making, except that trading hardware in for software opens a vast new field.

PROGRAM LISTING

00150 00160	* DTCT:	\$2P/20	WPM, \$28/ 0	15WPM, \$68/10WPM
00170	*	011	· ·	
20180 4004	4 PIAD	FCU	\$4884	CUTPUTS
20192 4025		ECU	\$4005	
00230 4026		FCU	\$4006	INPUTS
00216 460	7 PIBC	EQU	\$4027	
00220 0071		ECU	\$7F	
00230 0021	P DTCT	EQU	\$27	DIT COUNT
66546	*			
00250 0000		ORG	\$2	
60262 0020 000		BM3	1	
20270 2021 2002		RMB	2 2 2 2	
66586 6663 6663		RMP	2	
00290 0005 000		RMP	2	
60306 3067 000		RMB	2	
66316 8638 8683		RMB	1	
66356 406V 600		RMB	1 .	
00330	*			
00340 8000		OPG	\$8 ୧୧୧	
ee350 8000 01	START	NCP		
06366 8001 6E		SEI		SET INT MASK
00370 9002 CF 1		LDX	#\$FF1F	ALL OUTPUTS
	4004	STX	PIAD	IN A SIDE
	001F	LDX	#51F	ALL INPUTS
	4005	STX	PIBD	IN E SIDE
	007F	LDS	#STK	SET STACK IDENTIFY
	8190	LDX	#IDENT	
	8145	JSR	SENCO #RFSET	IDENT CODE CODE IDENT
00440 8017 CE 8		LDX JSR	SENCO	SEND CODE
PACADA SAIN ED S	#14J	124	SENCO	SEND CODE

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132 INTERFACE AGE

#\$7A6 1959 CTS UNITIM 500 MICRO SUBTRACT 1 DELX DO IT AGAIN, SAM! #BEEPR? POINT CODE SENCO SEND IT #BEEPR1 POINT *-6 SEND IT \$-6	\$21,\$40,4 \$70,\$50,\$0C,\$60,\$70,\$78	\$21,\$48,\$B@,\$48,\$21,\$28,\$48,4	\$21,\$68,\$5@,\$D@,\$E@,\$21,\$88,\$B8	\$21,\$B0,\$0C,\$90,\$28,4	\$83F8 2 2 2 2 1 1	START
DELONE LDX DELX BSR BNE RTS RTS BEEP? LDX RTS RTS A RT	BETPR1 FCB IDENT FCB	FCB	RESET FCB	FCB		FDB FNB
CE 07A6 8D 8D 26 FB 39 CE 8189 CE 818D 29 CE 818D 20 F8	818B 21 818C 40 818D 21 818E 40 818F 04 819F 70 8192 6C 8193 6C			81A2 10 81A2 21 81A4 88 81A5 B8 62450 81A6 21 81A7 B0	81A8 0C 81A9 90 81AA 28 81AB 24 82470 82470 82480 8378 82490 8378 82590 8379 82590 8379	83FF 8000
NC, GET OUT YES, GET TIME DEC IT FUT IT PACE IS IT=67 I.D. COUNT IDENTIFY CCDE YES, SEND I.D. SET CLOCK CLEAR INT	1 SEC GO DELAY (1' PAUSE SIGNAL GO DELAY (2: START OVER	READ INPUTS READ RX BIT TAILGATED DELAY 1 SEC CONTINUE	INPUTS RECEIVER BIT CONTINUE DECREMENT MORE DELAY	RFAD CONDX MASK TURN IT CFF	3 BEEPS 3 BEEPS DELAY 3 SFC READ RX BIT GET RX BIT DELAY 5 SEC RX OFF, GO START	(520 MICROSEC) SUBTRACT 1 NOT=0, REPEAT
NZ MINTEN MINTEN NZ TXFLG IDFIV OUTI #IDFIV OUTI #IDFIV FIBB FIBB FIBB	#\$B290 TIDLA BEEP1 #\$FFFF TIDLAY #\$5562 TIDLAY	PIBD #1 TLGATF TLDLA	FIBD #1 RECON TLDLAY	PIAD #\$7F PIAD TXFLG	BEEPS BEERS DELS TXOFE FIPD #1 HOLDOF RUN	#\$4A UNITI
PECTER STANDED TO THE	XXXXXXXXX QXXXXXX QXXXXXX QXXXXXX QXXXXX QXXXX QXXXX QXXX QXXX QXXX QXXX QX Q	LUA BAND BAND BANE BANE BANE BANE	Y LUDA AND BNE BNE BNE BTS	LDA B AND B STA B CIR	JSR JSR BSR LDA AND B BSR MP	M LUA DUCA FNE G
	TAIL	TLDLA	LDLA			UNITI
955 27 0A 997 DE 01 997 DE 01 997 DE 01 997 DE 01 991 77 000 991 77 000 991 77 000 991 77 000 991 77 000 991 DE 03 991 DE 03	PA CE E296 ED BD 10 BF ED 8184 CE CE FFFF C5 BD 13 C7 CE 5560 C7 CE 5560 C7 CE 5560	CF F6 4006 D2 C4 01 D4 26 AA D6 09 D7 26 F6 D9 39	DA F6 4006 DD C4 01 DF 26 9A E1 09 E2 26 F6	ES F6 4004 E8 C4 7F EA F7 4004 ED 7F 0009	F1 ED 8178 F7 8D 75 F9 8D EA F9 ED EA F9 EC 470 F7 EC 570 F7 EC 570 F7 EC 50 F7 EC 5	87 CE 4A 89 SA 2A 26 FD
01056 809 61056 809 61076 869 61109 869 91100 809 91110 80A 611136 80A 611176 80A 611176 80A 611176 80A 611176 80A 611176 80A 611176 80A 611176 80A 611176 80A			2544444	1466 86 1466 86 1486 88 1489 88 1566 83	1528 88 88 1558 88 88 1558 88 88 1558 88 81 1558 88 81 1558 88 81 1558	1620 81 1630 81 1640 81